

# Post-processing techniques in electronic structure calculations with DFTK.jl

**Gaspard Kemlin**

<https://gkemlin.pages.math.cnrs.fr/>

LAMFA, Université de Picardie Jules Verne – CNRS UMR 7352

Joint works with Eric Cancès, Geneviève Dusson and Antoine Levitt.

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## Discrete formulation of KS-DFT

- Mathematical formulation

- Optimality conditions

## Post-processing techniques for KS-DFT: error estimates and refinement

- Computational framework and linearization

- Error bounds for interatomic forces based on linearization

## Implementation in DFTK.jl

## Conclusion

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# General framework

We seek the ground-state energy and density by solving a constrained minimization problem:

$$E(P) := \underbrace{\text{Tr}(H_0 P)}_{\text{linear term}} + \underbrace{E_{\text{nl}}(P)}_{\text{nonlinear term}}$$

- ▶  $P \in \mathbb{C}_{\text{herm}}^{N \times N}$  is a trial density matrix;
- ▶  $N$  is the dimension of the approximation space (linked to the cut-off energy  $E_{\text{cut}}$  in DFTK.jl);
- ▶  $H_0 = -\frac{1}{2}\Delta + V$  is the core Hamiltonian;
- ▶  $E_{\text{nl}}$  models the electron-electron interaction, depending on the chosen DFT model.

## Kohn–Sham equations with LDA

Obtained as the Euler–Lagrange equations of (1):

$$\left\{ \begin{array}{l} \underbrace{\left(-\frac{1}{2}\Delta + V_{\text{nuc}}\right)}_{\text{linear term}} \varphi_n + \underbrace{V_{\text{Hxc}}(\rho)}_{\text{nonlinear term}} \varphi_n = \varepsilon_n \varphi_n, \\ \langle \varphi_n, \varphi_m \rangle = \delta_{nm}, \\ \rho = \sum_{n=1}^{N_{\text{el}}} |\varphi_n|^2. \end{array} \right.$$

(1)

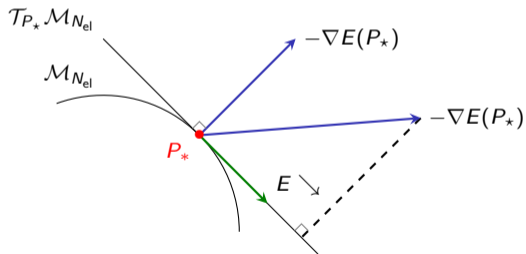
$$\min_{P \in \mathcal{M}_{N_{\text{el}}}} E(P) = \text{Tr}(H_0 P) + E_{\text{nl}}(P),$$
$$\mathcal{M}_{N_{\text{el}}} := \left\{ P \in \mathbb{C}^{N \times N} \mid P = P^*, \text{Tr}(P) = N_{\text{el}}, P^2 = P \right\}.$$

## Geometrical aspects – First-order condition

$$\min_{P \in \mathcal{M}_{N_{\text{el}}}} E(P) = \text{Tr}(H_0 P) + E_{\text{nl}}(P)$$

The first-order optimality condition is  $R(P_\star) := \nabla_{\mathcal{M}_{N_{\text{el}}}} E(P_\star) = \Pi_{P_\star}(H_\star) = 0$ , which gives, with  $H_\star = H(P_\star)$ ,

$$P_\star H_\star (1 - P_\star) = (1 - P_\star) H_\star P_\star = 0.$$



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- ▶  $[H_\star, P_\star] = 0 \Rightarrow H_\star$  and  $P_\star$  can be codiagonalized;
  - ▶ if  $(\varphi_i)_{1 \leq i \leq N_{\text{el}}}$  is an o.n.b. of eigenvectors of  $H_\star$  ordered by nondecreasing eigenvalues, then  $P_\star = \sum_{i \in \mathcal{I}} \varphi_i \varphi_i^*$ , with  $\mathcal{I}$  the set of occupied orbitals;
  - ▶  $\mathcal{I} \subset \{1, \dots, N_{\text{el}}\}$  and  $|\mathcal{I}| = N_{\text{el}}$ :
    - ▶  $\mathcal{I} = \{1, \dots, N_{\text{el}}\}$ : *Aufbau* principle;
    - ▶  $\mathcal{I} = \{1, \dots, N_{\text{el}}\}$  and  $\varepsilon_{N_{\text{el}}} < \varepsilon_{N_{\text{el}}+1}$ : strong *Aufbau* principle.
- In the decomposition  $\mathcal{H} = \text{Ran}(P_\star) \oplus \text{Ran}(1 - P_\star)$ , assuming the *Aufbau* principle

$$H_\star = \begin{array}{ccc} \leftarrow & \mathcal{I} & \rightarrow \bar{\mathcal{I}} \\ \begin{bmatrix} \varepsilon_1 & & & \\ & \ddots & & \\ & & \varepsilon_{N_{\text{el}}} & \\ & & & \ddots \end{bmatrix} & & \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \vdots \end{bmatrix} \end{array}, \quad P_\star = \begin{bmatrix} \mathcal{I} & \bar{\mathcal{I}} \\ \mathbf{1}_{N_{\text{el}}} & \mathbf{0} \\ 0 & 0 \end{bmatrix}$$

## Geometrical aspects – Second-order condition

$$\min_{P \in \mathcal{M}_{N_{\text{el}}}} E(P) = \text{Tr}(hP) + E_{\text{nl}}(P)$$

The second-order optimality condition reads (under reasonable assumptions)

$$\forall X \in \mathcal{T}_{P_\star} \mathcal{M}_{N_{\text{el}}}, \quad \left\langle X, [\mathbf{D}_{\mathcal{M}_{N_{\text{el}}}^2} E(P_\star)]X \right\rangle_{\mathbb{F}} \geq \eta \|X\|_{\mathbb{F}}^2, \quad \text{with} \quad \mathbf{D}_{\mathcal{M}_{N_{\text{el}}}^2} E(P_\star) = (\mathbf{\Omega}_\star + \mathbf{K}_\star)$$

- ▶  $\mathbf{K}_\star = \Pi_{P_\star} \nabla^2 E(P_\star) \Pi_{P_\star}$  is the classical Hessian;
- ▶ the operator  $\mathbf{\Omega}_\star : \mathcal{T}_{P_\star} \mathcal{M}_{N_{\text{el}}} \rightarrow \mathcal{T}_{P_\star} \mathcal{M}_{N_{\text{el}}}$  is defined by,

$$\forall X \in \mathcal{T}_{P_\star} \mathcal{M}_{N_{\text{el}}}, \quad \mathbf{\Omega}_\star(X) := -[P_\star, [\nabla E(P_\star), X]].$$

- ▶  $\mathbf{D}_{\mathcal{M}_{N_{\text{el}}}^2} E(P_\star) = \mathbf{\Omega}_\star + \mathbf{K}_\star$  can be interpreted as the Hessian of the energy on the manifold,  $\mathbf{\Omega}_\star$  represents the influence of the curvature. Can also be seen as the Hessian of the Lagrangian.

## Structure of $\Omega_\star$

Let  $(\varphi_i, \varepsilon_i)_{1 \leq i \leq N_{\text{el}}}$  be an eigendecomposition of  $H_\star$ . Recall, if  $\mathcal{H} = \text{Ran}(P_\star) \oplus \text{Ran}(1 - P_\star)$ ,

$$P_\star = \begin{bmatrix} \mathbf{1}_{N_{\text{el}}} & 0 \\ 0 & 0 \end{bmatrix} \quad \text{and} \quad \mathcal{TM}_{N_{\text{el}}} := \left\{ X = \begin{bmatrix} 0 & \times^\star \\ \times & 0 \end{bmatrix} \right\}.$$

Then

- ▶ for  $i \in \mathcal{I}$  and  $a \notin \mathcal{I}$

$$(\Omega_\star X)_{ia} = (\varepsilon_a - \varepsilon_i)X_{ia} \quad \text{and} \quad (\Omega_\star X)_{ai} = (\varepsilon_a - \varepsilon_i)X_{ai};$$

- ▶ the gap  $\min_{a \notin \mathcal{I}} \varepsilon_a - \max_{i \in \mathcal{I}} \varepsilon_i$  is the smallest eigenvalue of  $\Omega_\star$ .

**Remark 1:** if the *Aufbau* principle is satisfied, then the gap is  $\varepsilon_{N_{\text{el}}+1} - \varepsilon_{N_{\text{el}}}$ .

**Remark 2:**  $\Omega_\star = -\chi_0^{-1}$ , the 4pt-independent particle susceptibility operator<sup>1</sup>.

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<sup>1</sup>used in response calculations in DFTK.jl, cf. E. Cancès, Eric, M.F. Herbst, G. Kемlin, A. Levitt, and B. Stamm. *Numerical Stability and Efficiency of Response Property Calculations in Density Functional Theory*. *Letters in Mathematical Physics* 113(1):21 (2023).



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Mathematical formulation

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Computational framework and linearization

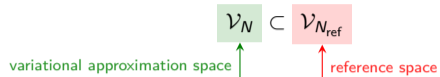
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## Computational framework

We consider a hierarchy of two discretization spaces with  $N \ll N_{\text{ref}}$  :



The problem becomes:

$$\min_{P \in \mathcal{M}_{N_{\text{el}}, N}} \text{Tr}(hP) + E_{\text{nl}}(P), \quad \mathcal{M}_{N_{\text{el}}, N} := \{P \in \mathbb{C}^{N \times N} \mid P = P^*, \text{Tr}(P) = N_{\text{el}}, P^2 = P\}.$$

- ▶ For convergence analysis and standard computations (ground-state energy and density, response calculations, ...), we work in  $\mathcal{V}_N$ .
- ▶ For error estimation :
  1. we find a solution  $P \in \mathcal{M}_{N_{\text{el}}, N} \subset \mathbb{C}^{N \times N} \subset \mathbb{C}^{N_{\text{ref}} \times N_{\text{ref}}}$  in the approximation space  $\mathcal{V}_N$  (for instance with a SCF algorithm);
  2. we try to estimate the error w.r.t.  $P_* \in \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}} \subset \mathbb{C}^{N_{\text{ref}} \times N_{\text{ref}}}$ , the solution in the reference space  $\mathcal{V}_{N_{\text{ref}}}$ , for a computational cost at most equivalent as for obtaining  $P$ .

## Linearization

Recall that  $\mathbf{\Omega}_\star + \mathbf{K}_\star \in \mathcal{L}(\mathcal{T}_{P_\star} \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}})$  is the Jacobian of  $P \mapsto R(P) = \Pi_P \nabla E(P)$  at  $P_\star$ :

$$\Pi_P \nabla E(P) \approx \Pi_{P_\star} \nabla E(P_\star) + (\mathbf{\Omega}_\star + \mathbf{K}_\star)(P - P_\star) + o(\|P - P_\star\|_F).$$

As  $\Pi_{P_\star} \nabla E(P_\star) = 0$ , with  $R(P)$  the residual, *in the linear regime*,

$$\Pi_P(P - P_\star) \approx (\mathbf{\Omega}_\star + \mathbf{K}_\star)^{-1} R(P)$$

## Linearization

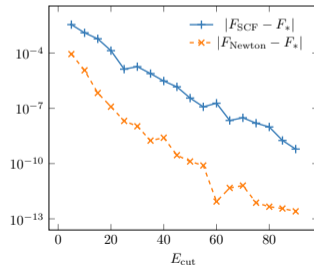
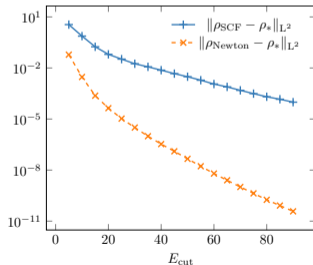
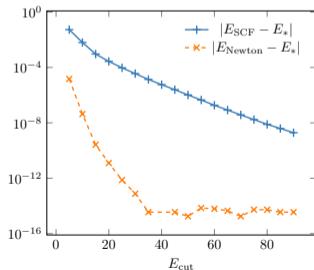
Recall that  $\mathbf{\Omega}_\star + \mathbf{K}_\star \in \mathcal{L}(\mathcal{T}_{P_\star} \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}})$  is the Jacobian of  $P \mapsto R(P) = \Pi_P \nabla E(P)$  at  $P_\star$ :

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**Numerical check:** the linear regime is established if  $P - (\mathbf{\Omega}_\star + \mathbf{K}_\star)^{-1} R(P)$  is much closer to  $P_\star$ .



## Interatomic forces (at the discrete level)

Recall  $E(P) = \text{Tr}(hP) + E_{\text{nl}}(P)$  with  $h = -\frac{1}{2}\Delta + V : V = V(X)$  for  $X = (X_j) \in \omega^M$  positions of atomic nuclei  
 $\Rightarrow E(P) = E(X, P)$ .

**Hellmann–Feynman:**

$$P_{\star} = \operatorname{argmin} \left\{ E(X_0, \tilde{P}) \mid \tilde{P} \in \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}} \right\};$$

$$F_{\star} = F(P_{\star}) = \left[ -\nabla_{X_{j\alpha}} E(X_0, P_{\star}) \right]_{j=1, \dots, M}^{\alpha=1, 2, 3} = \left[ -\text{Tr} \left( \partial_{X_{j\alpha}} V(X_0) P_{\star} \right) \right]_{j=1, \dots, M}^{\alpha=1, 2, 3}.$$

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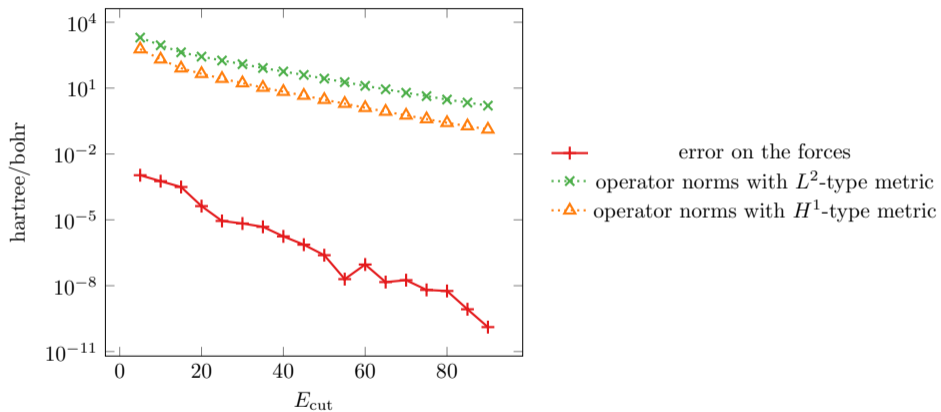
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First naive error bound for the interatomic forces  $F(P)$ :

$$\begin{aligned} \|F(P) - F_{\star}\| &\leq \|dF(P_{\star})\|_{\text{op}} \|P - P_{\star}\|_{\text{F}} \\ &\leq \|dF(P_{\star})\|_{\text{op}} \|(\Omega_{\star} + \mathbf{K}_{\star})^{-1}\|_{\text{op}} \|R(P)\|_{\text{F}}. \end{aligned}$$

Error on the forces for a silicon crystal.



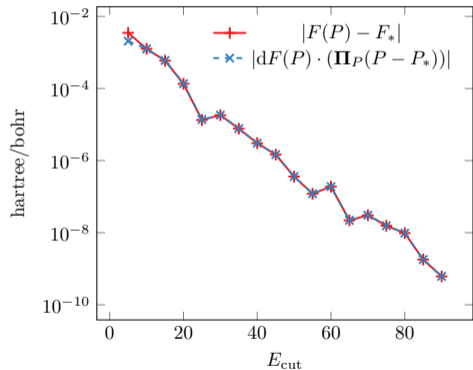
In the asymptotic regime:

$$P - P_\star \approx (\Omega + K)^{-1} R(P) \approx M^{-1} R(P) \quad \text{in energy norm.}$$

↑ not computable      ↑ generalization of  $\Omega_\star + K_\star$  to  $P \neq P_\star$  : computable but expensive      ↑ computable and cheap

Replace the error  $F(P) - F_\star$  by  $dF(P) \cdot (\Pi_P(P - P_\star))$ .

↪ Good, but not usable in practice ( $P_\star$  is unknown).





In the asymptotic regime:

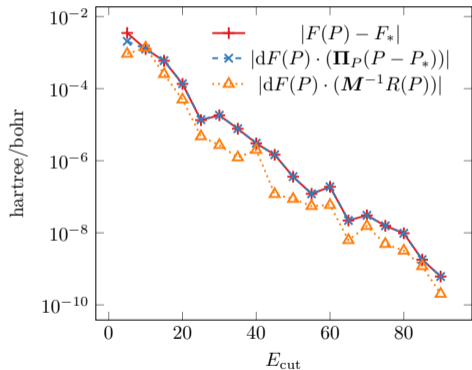
$$\underbrace{P - P_\star}_{\text{not computable}} \approx \underbrace{(\Omega + \mathbf{K})^{-1}R(P)}_{\text{generalization of } \Omega_\star + \mathbf{K}_\star \text{ to } P \neq P_\star : \text{computable but expensive}} \approx \underbrace{\mathbf{M}^{-1}R(P)}_{\text{computable and cheap}} \quad \text{in energy norm.}$$

Replace the error  $F(P) - F_\star$  by  $dF(P) \cdot (\Pi_P(P - P_\star))$ .

↪ Good, but not usable in practice ( $P_\star$  is unknown).

Replace  $P - P_\star$  by  $\mathbf{M}^{-1}R(P)$ , with  $\mathbf{M} \sim -\frac{1}{2}\Delta + 1$ .

↪ Better, but still not satisfying.

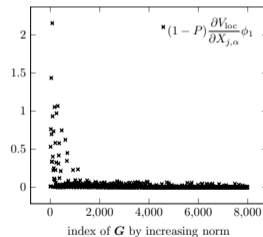
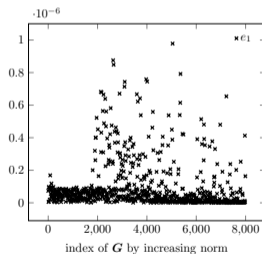
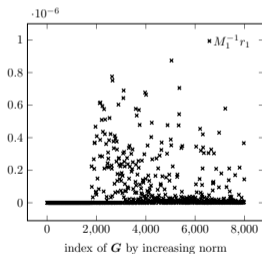


## Frequency splitting

Let  $P \in \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}}$ , then  $\mathcal{T}_P \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}}$  can be split into low and high frequencies:

$$\mathcal{T}_P \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}} = \underbrace{\Pi_N \mathcal{T}_P \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}}}_{\text{low frequencies}} \oplus \underbrace{\Pi_N^\perp \mathcal{T}_P \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}}}_{\text{high frequencies}}.$$

If  $P$  is a solution of the variational problem in  $\mathcal{V}_N$ , then  $R(P), M^{-1}R(P) \in \Pi_N^\perp \mathcal{T}_P \mathcal{M}_{N_{\text{el}}, N_{\text{ref}}}$ .



$\rightsquigarrow dF(P)$  is mainly supported on low frequencies.

## Enhanced error bounds

We decompose the error/residual relation onto  $\Pi_N \mathcal{T}_P \mathcal{M}_{N_{el}, N_{ref}} \oplus \Pi_N^\perp \mathcal{T}_P \mathcal{M}_{N_{el}, N_{ref}}$  to get

$$\begin{bmatrix} (\mathbf{\Omega} + \mathbf{K})_{11} & (\mathbf{\Omega} + \mathbf{K})_{12} \\ (\mathbf{\Omega} + \mathbf{K})_{21} & (\mathbf{\Omega} + \mathbf{K})_{22} \end{bmatrix} \begin{bmatrix} P_1 - P_{*1} \\ P_2 - P_{*2} \end{bmatrix} = \begin{bmatrix} R_1 \\ R_2 \end{bmatrix}.$$

As the kinetic energy is dominating for high-frequencies, we approximate

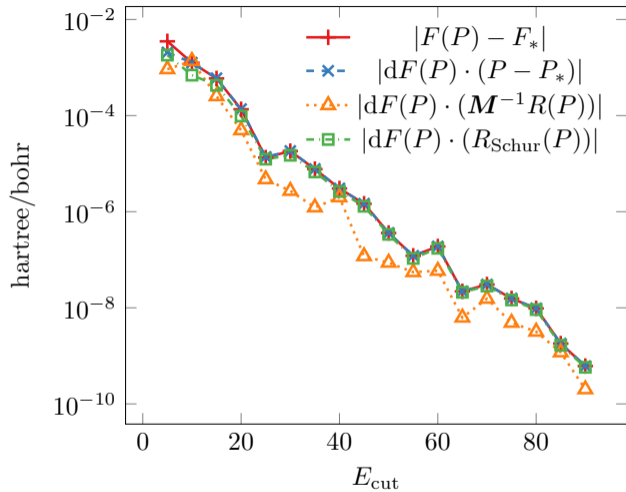
$$(\mathbf{\Omega} + \mathbf{K})_{21} \approx 0 \quad \text{and} \quad (\mathbf{\Omega} + \mathbf{K})_{22} \approx \mathbf{M}_{22},$$

and thus

$$\begin{bmatrix} (\mathbf{\Omega} + \mathbf{K})_{11} & (\mathbf{\Omega} + \mathbf{K})_{12} \\ 0 & \mathbf{M}_{22} \end{bmatrix} \begin{bmatrix} P_1 - P_{*1} \\ P_2 - P_{*2} \end{bmatrix} = \begin{bmatrix} R_1 \\ R_2 \end{bmatrix}.$$

This yields a new residual, which requires only an inversion on the coarse grid ( $\mathbf{M}_{22}$  being easy to invert):

$$R_{\text{Schur}}(P) = \begin{bmatrix} (\mathbf{\Omega} + \mathbf{K})_{11}^{-1} (R_1 - (\mathbf{\Omega} + \mathbf{K})_{12} \mathbf{M}_{22}^{-1} R_2) \\ \mathbf{M}_{22}^{-1} R_2 \end{bmatrix}.$$



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## Conclusion and take-home messages

- ▶ With planewaves, the asymptotic regime is quickly established  $\Rightarrow$  linearization of KS equations is useful.
- ▶ Linearization can be used in a post-processing step:
  1. to estimate the error on QoI:  $Q(P) - Q(P_*) \approx dQ(P) \cdot R_{\text{Schur}}(P)$  up to higher order terms;
  2. to refine the obtained solution:  $Q(P) - dQ(P) \cdot R_{\text{Schur}}(P)$  is a better approximation of  $Q(P_*)$ .
- ▶ Implemented by default in DFTK.jl in a simplified framework (PR by Bruno Ploumhans). To be released in the next version.

### Perspectives and ideas:

- ▶ Metallic systems (positive gap assumption does not hold anymore).
- ▶ Other quantities of interest than interatomic forces.
- ▶ Fully guaranteed bounds (on the energy, taking into account both SCF and discretization errors, cf. poster by Rafael Lainez and me).



Pluto notebook

### Some references on post-processing techniques:

- ▶ E. Cancès, G. Dusson, Y. Maday, B. Stamm, and M. Vohralik. *Post-Processing of the Planewave Approximation of Schrödinger Equations. Part I: Linear Operators*. IMA Journal of Numerical Analysis 41(4):2423-55 (2021).
- ▶ G. Dusson. *Post-Processing of the Plane-Wave Approximation of Schrödinger Equations. Part II: Kohn–Sham Models*. IMA Journal of Numerical Analysis 41(4):2456-87 (2021).
- ▶ E. Cancès, G. Dusson, G Kemlin, and A. Levitt. *Practical Error Bounds for Properties in Plane-Wave Electronic Structure Calculations*. SIAM Journal on Scientific Computing 44(5):B1312-40 (2022).

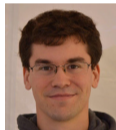
Merci!



Eric  
Cancès  
(ENPC & Inria)



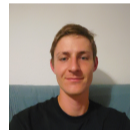
Geneviève  
Dusson  
(CNRS & UBFC)



Antoine  
Levitt  
(LMO)



Michael F.  
Herbst  
(EPFL)



Bruno  
Ploumhans  
(EPFL)